

Directions: For each skill area, clearly mark the box that best describes the team's accomplishments. If the team does not demonstrate skill in a particular area, then put an 'X' in the first box for Not Demonstrated (ND). Please provide as many written comments as you can to acknowledge each team's hard work and to help teams improve. *When you have completed the evaluation, please circle the team's areas of strength.*

		Beginning	Developing	Accomplished	Exemplary
Mechanical Design	Durability	Evidence of structural integrity; ability to withstand rigors of competition			
	N	quite fragile; breaks a lot	frequent or significant faults/repairs	rare faults/repairs	sound construction; no repairs
	D				
	Mechanical Efficiency	Economic use of parts and time; easy to repair and modify			
	N	excessive parts or time to repair/modify	inefficient parts or time to repair/modify	appropriate use of parts and time to repair/modify	streamlined use of parts and time to repair/modify
D					
Mechanization	Mechanization	Ability of robot mechanisms to move or act with appropriate speed, strength and accuracy for intended tasks (propulsion and execution)			
	N	imbalance of speed, strength and accuracy on most tasks	imbalance of speed, strength and accuracy on some tasks	appropriate balance of speed, strength and accuracy on most tasks	appropriate balance of speed, strength and accuracy on every task
	D				
Programming	Programming Quality	Programs are appropriate for the intended purpose and would achieve consistent results, assuming no mechanical faults			
	N	would not achieve purpose	would not achieve purpose	should achieve purpose	should achieve purpose
	D	AND would be inconsistent	OR would be inconsistent	repeatedly	every time
	Programming Efficiency	Programs are modular, streamlined, and understandable			
	N	excessive code and difficult to understand	inefficient code and challenge to understand	appropriate code and easy to understand	streamlined code and easy for anyone to understand
D					
Automation/Navigation	Automation/Navigation	Ability of the robot to move or act as intended using mechanical and/or sensor feedback (with minimal reliance on driver intervention and/or program timing)			
	N	frequent driver intervention to aim AND retrieve robot	frequent driver intervention to aim OR retrieve robot	robot moves/acts as intended repeatedly w/ occasional driver intervention	robot moves/acts as intended every time with no driver intervention
	D				
Strategy & Innovation	Design Process	Ability to develop and explain improvement cycles where alternatives are considered and narrowed, selections tested, designs improved (applies to programming as well as mechanical design)			
	N	organization AND explanation need improvement	organization OR explanation need improvement	systematic and well-explained	systematic, well-explained and well-documented
	D				
	Mission Strategy	Ability to clearly define and describe the team's game strategy			
	N	no clear goals AND no clear strategy	no clear goals OR no clear strategy	clear strategy to accomplish the team's well defined goals	clear strategy to accomplish most/all game missions
D					
Innovation	Innovation	Creation of new, unique, or unexpected feature(s) (e.g. designs, programs, strategies or applications) that are beneficial in performing the specified tasks			
	N	original feature(s) with no added value or potential	original feature(s) with some added value or potential	original feature(s) with the potential to add significant value	original feature(s) that add significant value
	D				
Strengths:		Mechanical Design	Programming	Strategy & Innovation	

Comments:

Comments:

Comments: